

Channel Quantization for Block Diagonalization with Limited Feedback in Multiuser MIMO Downlink Channels

Sung-Hyun Moon, Sang-Rim Lee, Jin-Sung Kim, and Inkyu Lee

Abstract: Block diagonalization (BD) has been proposed as a simple and effective technique in multiuser multiple-input multiple-output (MU-MIMO) broadcast channels. However, when channel state information (CSI) knowledge is limited at the transmitter, the performance of the BD may be degraded because inter-user interference cannot be completely eliminated. In this paper, we propose an efficient CSI quantization technique for BD precoded systems with limited feedback where users supported by a base station are selected by dynamic scheduling. First, we express the received signal-to-interference-plus-noise ratio (SINR) when multiple data streams are transmitted to the user, and derive a lower bound expression of the expected received SINR at each user. Then, based on this measure, each user determines its quantized CSI feedback information which maximizes the derived expected SINR, which comprises both the channel direction and the amplitude information. From simulations, we confirm that the proposed SINR-based channel quantization scheme achieves a significant sum rate gain over the conventional method in practical MU-MIMO systems.

Index Terms: Block diagonalization (BD), limited feedback, multiple-input multiple-output (MIMO) broadcast channel, signal-to-interference-plus-noise ratio (SINR).

I. INTRODUCTION

Over the past decade, wireless communication systems have succeeded in significantly improving spectral efficiency through the aid of multiuser multiple-input multiple-output (MU-MIMO) techniques. Especially, transmission techniques for downlink broadcast channels (BCs) have been extensively studied in line with Costa's dirty paper coding (DPC) results [1]. From an information theoretic viewpoint, the capacity region of MIMO Gaussian BCs has been characterized based on the DPC approach [2], [3].

In parallel with theoretical developments, practical MU-MIMO schemes have been proposed to approach the maxi-

um capacity gains of MIMO BCs. The most popular ones are zero-forcing beamforming (ZFBF) [4] and block diagonalization (BD) [5] which support multiple users at the same time and frequency resource by pre-canceling inter-user interference using a simple inverse or inverse-like operation. Also, in order to resolve an issue of power boost at the transmitter, regularized type ZFBF and BD precoders have been introduced [6], [7]. Assuming perfect knowledge of channel state information (CSI) at the transmitter, these schemes achieve fairly good sum rate performance gains when combined with efficient scheduling algorithms [4], [8].

However, in most practical cellular systems, especially with the frequency division duplex (FDD) mode, it is a great burden to obtain the accurate CSI of users over the whole operating bandwidth at the base station (BS). In practice, the CSI is quantized based on a predetermined codebook and only the index of the selected codeword is fed back to the BS. In [9] and [10], the performance of a ZFBF based on limited feedback with or without scheduling was analyzed for vector channels. For the MIMO case, it was shown that receive combining provides a large gain by reducing the amount of channel quantization errors [11], [12]. Although the channel feedback strategies for the BD was also discussed in [13], issues regarding the user scheduling were not taken into account.

Recently, a channel quantization technique has been presented in [14] for the FDD cellular systems where the BD precoding and user scheduling are employed to support a large number of users in a cell. In order to fully utilize multiuser diversity gains, the authors proposed a useful metric for channel quality measurements based on the derivation of the expected received signal-to-interference-plus-noise ratio (SINR) at each user. Based on this prior work, in this paper, we generalize the channel quality indicator (CQI) feedback scheme provided in [14] to systems with minimum mean-square error (MMSE) receivers and an arbitrary number of data streams (not larger than the number of receive antennas) per each user.

Also, we discuss how to choose the best codeword index in the codebook together with the CQI based on the proposed expected SINR. Then, an analysis for the outage probability of the proposed expected SINR metric is newly provided. From simulations, we confirm that the proposed SINR-based channel quantization scheme achieves a significant sum rate performance gain over the conventional feedback method in practical MU-MIMO systems.

The remainder of this paper is organized as follows. In Section II, we introduce the system model with limited CSI feedback and review the BD in Section III. Section IV describes the

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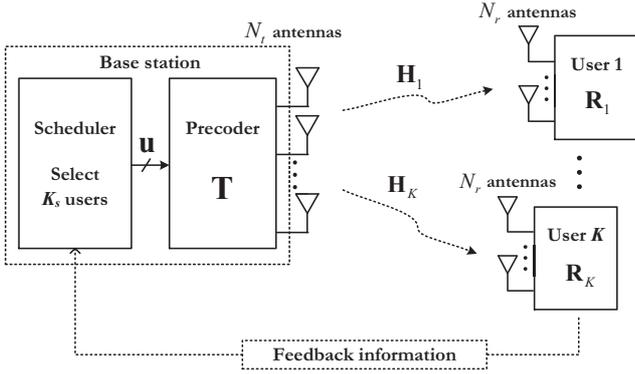


Fig. 1. Block diagram of downlink multiuser MIMO systems with limited feedback.

proposed limited feedback scheme for the BD based on the estimation of the received SINR, and the outage probability analysis is presented in Section V. In Section VI, the sum rate performance is evaluated through simulations. Finally, the paper ends with conclusions in Section VII.

Throughout this paper, we use the following notations. Normal letters represent scalar quantities, bold face lowercase letters indicate vectors, and boldface uppercase letters designate matrices. The superscripts $(\cdot)^T$ and $(\cdot)^H$ stand for transpose and Hermitian transpose, respectively. The two-norm of a vector is represented by $\|\cdot\|$ and the Frobenius norm of a matrix is denoted by $\|\cdot\|_F$. The determinant and the trace of a matrix are given by $\det(\cdot)$ and $\text{Tr}(\cdot)$, respectively, and \mathbf{I}_d indicates an identity matrix of size d .

II. SYSTEM MODEL

We consider a MIMO BC where K users exist in a cell. We assume that the BS has N_t transmit antennas and each user is equipped with N_r receive antennas as shown in Fig. 1. In each time slot, the BS performs scheduling to select K_s users among K users and transmits N_s data streams equally to all the selected K_s users, where K_s is limited to $K_s \leq N_t/N_s$ such that the condition for orthogonal transmission among users is satisfied [15].

First, we define the data symbol vector $\mathbf{u}_k \in \mathbb{C}^{N_s \times 1}$ and the precoding matrix $\mathbf{T}_k \in \mathbb{C}^{N_t \times N_s}$ for the k th user ($k = 1, \dots, K_s$). Then, by denoting $\mathbf{T} = [\mathbf{T}_1 \dots \mathbf{T}_{K_s}]$ and $\mathbf{u} = [\mathbf{u}_1^T \dots \mathbf{u}_{K_s}^T]^T$, the precoded signal vector $\mathbf{x} \in \mathbb{C}^{N_t \times 1}$ is given by $\mathbf{x} = \mathbf{T}\mathbf{u} = \sum_{k=1}^{K_s} \mathbf{T}_k \mathbf{u}_k$. Here, we assume that \mathbf{x} satisfies the total transmit power constraint $\text{Tr}(\mathbb{E}[\mathbf{x}\mathbf{x}^H]) \leq P$, where P represents the total transmit power at the BS. Assuming that all symbols of \mathbf{u} are independently generated with unit variance, \mathbf{T} is constrained to satisfy $\text{Tr}(\mathbf{T}\mathbf{T}^H) \leq P$.

Then, the received signal vector $\mathbf{y}_k \in \mathbb{C}^{N_r \times 1}$ for the k th user is determined as

$$\mathbf{y}_k = \mathbf{H}_k^H \mathbf{T}_k \mathbf{u}_k + \sum_{j=1, j \neq k}^{K_s} \mathbf{H}_k^H \mathbf{T}_j \mathbf{u}_j + \mathbf{n}_k \quad (1)$$

where $\mathbf{H}_k \in \mathbb{C}^{N_t \times N_r}$ is the channel matrix whose entries are independent and identically distributed (i.i.d.) complex Gaussian with $\mathcal{CN}(0, 1)$ and $\mathbf{n}_k \in \mathbb{C}^{N_r}$ denotes the additive white Gaussian noise (AWGN) vector with zero mean and covariance matrix $\mathbb{E}[\mathbf{n}_k \mathbf{n}_k^H] = \mathbf{I}_{N_r}$. It is assumed that each user has perfect knowledge of its own channel \mathbf{H}_k , which has full column rank.

At the receiver, the k th user estimates the transmitted signal $\hat{\mathbf{u}}_k \in \mathbb{C}^{N_s \times 1}$ from the receive filter output as $\hat{\mathbf{u}}_k = \mathbf{R}_k^H \mathbf{y}_k$, where $\mathbf{R}_k \in \mathbb{C}^{N_r \times N_s}$ indicates the receive combining filter at user k . We adopt the linear MMSE receiver for \mathbf{R}_k

$$\mathbf{R}_k = \left(\mathbf{I}_{N_r} + \rho \sum_{j=1, j \neq k}^{K_s} \mathbf{H}_k^H \mathbf{T}_j \mathbf{T}_j^H \mathbf{H}_k \right)^{-1} \mathbf{H}_k^H \mathbf{T}_k \quad (2)$$

under the assumption that $\{\mathbf{H}_k^H \mathbf{T}_j\}_{j=1}^{K_s}$ can be estimated at the receiver using dedicated pilot symbols where $\rho = P/N_t$ denotes the transmit power applied to each symbol.

Then, the k th user's received SINR corresponds to the desired signal vector \mathbf{u}_k is defined from (1) as

$$\text{SINR}_k = \frac{\rho \|\mathbf{H}_{e,k}^H \mathbf{T}_k\|_F^2}{\|\mathbf{R}_k\|_F^2 + \sum_{j=1, j \neq k}^{K_s} \rho \|\mathbf{H}_{e,k}^H \mathbf{T}_j\|_F^2} \quad (3)$$

where $\mathbf{H}_{e,k} = \mathbf{H}_k \mathbf{R}_k \in \mathbb{C}^{N_t \times N_s}$ represents the effective channel combined with \mathbf{R}_k and \mathbf{T}_k satisfies $\text{Tr}(\mathbf{T}_k \mathbf{T}_k^H) = N_s$. The Frobenius norm expression in (3) is employed since each data signal \mathbf{u}_k may consist of more than one symbol ($N_s > 1$) [16], [17], which reduces to the conventional SINR definition for $N_s = 1$.

Since the feedback link is bandwidth-constrained, users perform quantization on their effective CSI $\mathbf{H}_{e,k}$ before feeding back to the BS. The quantized CSI is composed of channel directional information (CDI) and CQI, each of which are denoted by $\hat{\mathbf{H}}_{e,k} \in \mathbb{C}^{N_t \times N_s}$ and γ_k . The CDI accounts for the spatial direction of the MIMO channel, i.e., the subspace spanned by the column vectors of $\mathbf{H}_{e,k}$, and the CQI indicates the level of the fading amplitudes. The most well-known and widely used approach to handle the CDI is the use of a codebook, which is an application of the quantization problem on the Grassmann manifold [18], denoted as $\mathcal{G}(N_t, N_s)$ ¹. We consider a codebook \mathcal{C} composed of 2^B codeword matrices $\mathbf{W}_1, \dots, \mathbf{W}_{2^B} \in \mathbb{C}^{N_t \times N_s}$ whose column vectors are unit norm and orthogonal to each other. Due to its simplicity and analytical tractability, we employ random vector quantization (RVQ) for \mathcal{C} where $\mathbf{W}_1, \dots, \mathbf{W}_{2^B}$ are chosen independently and isotropically over \mathbb{C}^{N_t} [19]. On the other hand, the type of the CQI is relatively not well specified, especially for the case of multi-stream transmission ($N_s > 1$) where the effective channels $\mathbf{H}_{e,k}$ are matrices. This issue will be investigated in detail in Section IV.

III. REVIEW OF BLOCK DIAGONALIZATION

The BD transforms a multiuser MIMO channel into parallel single-user MIMO channels by suppressing inter-user interference [5]. Many papers regarding the BD assume that users have

¹The column space of a matrix $\mathbf{F} \in \mathbb{C}^{N_t \times N_s}$ is contained in $\mathcal{G}(N_t, N_s)$.

multiple receive antennas ($N_r > 1$) and each selected user receives full $N_s = N_r$ data streams. In this work, we consider a more general setting where an arbitrary number of N_s ($\leq N_r$) is supported for each user by adopting the receive combining filter \mathbf{R}_k . If N_s becomes one, the precoder reduces to the ZF beamforming.

In the BD procedure, we first seek a precoding matrix which eliminates inter-user interference, and then the channels for each user are decoupled into N_s parallel subchannels to achieve the maximum information rate. To suppress the interference term $\sum_{j \neq k} \mathbf{H}_{e,k}^H \mathbf{T}_j \mathbf{u}_j$ in (1) after the receive combining, the precoding matrix \mathbf{T}_k should satisfy

$$\mathbf{H}_{e,j}^H \mathbf{T}_k = \mathbf{0} \text{ for all } k \neq j. \quad (4)$$

In other words, \mathbf{T}_k should lie in the left nullspace of $\tilde{\mathbf{H}}_{e,k}$ where $\tilde{\mathbf{H}}_{e,k}$ is defined as

$$\tilde{\mathbf{H}}_{e,k} = [\mathbf{H}_{e,1} \cdots \mathbf{H}_{e,k-1} \quad \mathbf{H}_{e,k+1} \cdots \mathbf{H}_{e,K_s}].$$

Denote $\tilde{\mathbf{V}}_k^{(0)} \in \mathbb{C}^{N_t \times (N_t - L_k)}$ as the matrix which consists of orthonormal basis vectors of the left nullspace of $\tilde{\mathbf{H}}_{e,k}$ where $L_k = \text{rank}(\tilde{\mathbf{H}}_{e,k})$. Then, precoding with $\tilde{\mathbf{V}}_k^{(0)}$ can nullify the interference as $\mathbf{H}_{e,j}^H \tilde{\mathbf{V}}_k^{(0)} = \mathbf{0}$ for $j \neq k$ and forms the k th user's non-interfering block channel $\mathbf{H}_{e,k}^H \tilde{\mathbf{V}}_k^{(0)}$.

In order to decouple this block channel into N_s parallel subchannels, singular value decomposition (SVD) is performed on $\mathbf{H}_{e,k}^H \tilde{\mathbf{V}}_k^{(0)}$ as $\mathbf{H}_{e,k}^H \tilde{\mathbf{V}}_k^{(0)} = \mathbf{U}_k \mathbf{\Sigma}_k \mathbf{V}_k^H$. Then, the precoder $\tilde{\mathbf{T}}_k$ and the receiver $\tilde{\mathbf{R}}_k \in \mathbb{C}^{N_r \times N_s}$ are determined as $\tilde{\mathbf{T}}_k = \tilde{\mathbf{V}}_k^{(0)} \mathbf{V}_k$ and $\tilde{\mathbf{R}}_k = \mathbf{U}_k$, respectively. By assuming Gaussian codebook and combining with $N_s \times N_s$ diagonal power loading matrices Φ_k for $k = 1, \dots, K_s$, the sum rate for the BD can be written as

$$R_{\text{BD}} = \max_{\Phi_k} \sum_{k=1}^{K_s} \log \det (\mathbf{I}_{N_s} + \mathbf{\Sigma}_k^2 \Phi_k)$$

subject to $\sum_{k=1}^{K_s} \text{Tr}(\Phi_k) \leq P$. This is a well-known convex problem and the optimal solution Φ_k can be obtained using the water-filling method. Finally, we have the precoding matrix \mathbf{T} as $\mathbf{T} = [\tilde{\mathbf{T}}_1 \cdots \tilde{\mathbf{T}}_{K_s}] \Phi^{\frac{1}{2}}$ where $\Phi = \text{diag}(\Phi_1, \dots, \Phi_{K_s})$.

IV. SINR-BASED CHANNEL QUANTIZATION FOR BLOCK DIAGONALIZATION

When true channels are not perfectly known at the BS, the null constraint (4) is broken since the BD chooses the precoder orthogonal to the quantized channels, not the actual channels. Then, there remain residual interference signals among users, which degrades the sum rate performance especially in the high signal-to-noise ratio (SNR) regime [9]. Therefore, it is important to design the CDI and the CQI carefully in order to minimize the inter-user interference. In this section, motivated by this, we propose an efficient channel quantization strategy for the BD which decides a proper CDI and CQI feedback based on the received SINR defined in (3). For simplicity, we assume

uniform power allocation across data streams, i.e., $\Phi = \mathbf{I}_{K_s N_s}$, which is known to be asymptotically optimal at the high SNR region [20].

First, we recall a useful matrix decomposition provided in [13] for our effective channel $\mathbf{H}_{e,k}$. Let the eigenvalue decomposition (EVD) of $\mathbf{H}_{e,k} \mathbf{H}_{e,k}^H$ be given as

$$\mathbf{H}_{e,k} \mathbf{H}_{e,k}^H = \bar{\mathbf{H}}_{e,k} \mathbf{\Lambda}_{e,k} \bar{\mathbf{H}}_{e,k}^H \quad (5)$$

where $\mathbf{\Lambda}_{e,k} = \text{diag}(\lambda_{k,1}, \dots, \lambda_{k,N_s})$ consists of N_s non-zero eigenvalues of $\mathbf{H}_{e,k} \mathbf{H}_{e,k}^H$ and $\bar{\mathbf{H}}_{e,k} \in \mathbb{C}^{N_t \times N_s}$ is the matrix of the corresponding orthonormal basis vectors which span the column space of $\mathbf{H}_{e,k}$. Then, it was shown in [13] that $\bar{\mathbf{H}}_{e,k}$ can be decomposed as

$$\bar{\mathbf{H}}_{e,k} = \hat{\mathbf{H}}_{e,k} \mathbf{A}_k \mathbf{B}_k + \mathbf{S}_k \mathbf{C}_k \quad (6)$$

where $\mathbf{S}_k \in \mathbb{C}^{N_t \times N_s}$ indicates an orthonormal basis matrix which spans an isotropically distributed N_s -dimensional plane in the $(N_t - N_s)$ -dimensional left nullspace of $\hat{\mathbf{H}}_{e,k}$, $\mathbf{C}_k \in \mathbb{C}^{N_s \times N_s}$ denotes an upper triangular matrix with positive diagonal entries satisfying $\text{Tr}(\mathbf{C}_k^H \mathbf{C}_k) = d^2(\bar{\mathbf{H}}_{e,k}, \hat{\mathbf{H}}_{e,k})$ with $d(\cdot, \cdot)$ being a distance function on $\mathcal{G}(N_t, N_s)$, $\mathbf{A}_k \in \mathbb{C}^{N_s \times N_s}$ is unitary and $\mathbf{B}_k \in \mathbb{C}^{N_s \times N_s}$ is upper triangular which satisfies $\mathbf{B}_k^H \mathbf{B}_k = \mathbf{I}_{N_s} - \mathbf{C}_k^H \mathbf{C}_k$. Here, \mathbf{S}_k and \mathbf{C}_k are independent.

A. Conventional Feedback Scheme

For the CDI, a well-known quantization method is to choose a codeword which is the closest to the column space of \mathbf{H}_k , or the effective channel $\mathbf{H}_{e,k} = \mathbf{H}_k \mathbf{R}_k$ in our case, which can be expressed as [13]

$$\hat{\mathbf{H}}_{e,k} = \arg \min_{\mathbf{W}_i \in \mathcal{C}} d(\bar{\mathbf{H}}_{e,k}, \mathbf{W}_i). \quad (7)$$

In [13], the authors proposed to adopt the chordal distance for $d(\cdot, \cdot)$, which is one of common distance metrics between two subspaces. When the two subspaces are represented by $N_t \times N_s$ complex matrices \mathbf{F}_1 and \mathbf{F}_2 whose columns form an orthonormal basis in $\mathcal{G}(N_t, N_s)$, the chordal distance $d(\mathbf{F}_1, \mathbf{F}_2)$ is defined by

$$\begin{aligned} d(\mathbf{F}_1, \mathbf{F}_2) &= \frac{1}{\sqrt{2}} \|\mathbf{F}_1 \mathbf{F}_1^H - \mathbf{F}_2 \mathbf{F}_2^H\|_F \\ &= \sqrt{N_s - \text{Tr}(\mathbf{F}_1^H \mathbf{F}_2 \mathbf{F}_2^H \mathbf{F}_1)}. \end{aligned} \quad (8)$$

On the other hand, to the best of authors' knowledge, no proper definition on the CQI and its quantization exists for the BD precoded systems with $N_s \geq 2$. Even the information size of the CQI should be determined in this case. In this paper, we consider the CQI as a single real value, which we denote as γ_k , in terms of minimizing the feedback overhead. In that case, one natural choice for γ_k can be the Frobenius norm of the channel matrix given by

$$\gamma_k^{\text{norm}} = \|\mathbf{H}_{e,k}\|_F^2 = \text{Tr}(\bar{\mathbf{H}}_{e,k} \mathbf{\Lambda}_{e,k} \bar{\mathbf{H}}_{e,k}^H) = \text{Tr}(\mathbf{\Lambda}_{e,k}) \quad (9)$$

which indicates the sum of the effective channel gains $\sum_{j=1}^{N_s} \lambda_{k,j}$ of user k . These channel gains are mainly achievable when the CDI feedback is ideal and the interference term

in (1) is completely eliminated. Therefore, the metric (9) can be simply obtained, but may not be suitable with the quantized CDI. If (9) is adopted as the CQI feedback, the receive filter \mathbf{R}_k can be computed as N_s dominant right singular vectors of \mathbf{H}_k from the SVD operation.

B. Proposed SINR-Based Feedback Scheme

Now, we describe the proposed SINR-based channel quantization technique. Our original goal is to identify the CDI and the CQI which maximize the received SINR in (3). However, as pointed out in [14], the true values of the SINR cannot be estimated at the receiver, since users do not know the precoders $\{\mathbf{T}_k\}_{k=1}^{K_s}$ in the feedback stage which occurs before the user selection process. Therefore, we develop an expression of the expected SINR where the expectation is taken in terms of $\{\mathbf{T}_k\}_{k=1}^{K_s}$, which can be a useful performance measure in such MU-MIMO situations [10], [12].

By taking the expectation on (3) and applying Jensen's inequality with respect to its interference term, the expected SINR for the k th user, denoted by $\overline{\text{SINR}}_k$, is lower bounded as

$$\begin{aligned} \overline{\text{SINR}}_k &= \mathbb{E}_{\mathbf{T}_1, \dots, \mathbf{T}_{K_s}} [\text{SINR}_k] \\ &\geq \mathbb{E}_{\mathbf{T}_k} \left[\frac{\rho \text{Tr}(\mathbf{H}_{e,k}^H \mathbf{T}_k \mathbf{T}_k^H \mathbf{H}_{e,k})}{\|\mathbf{R}_k\|_F^2 + \sum_{j \neq k} \rho \text{Tr}(\mathbb{E}_{\mathbf{T}_j} [\mathbf{H}_{e,k}^H \mathbf{T}_j \mathbf{T}_j^H \mathbf{H}_{e,k}])} \right]. \end{aligned} \quad (10)$$

When greedy type user scheduling is employed, it is assumed that K_s chosen users are nearly orthogonal to each other as K grows large enough [4]. In that case, the subspace of \mathbf{T}_k is closely aligned to that of $\hat{\mathbf{H}}_{e,k}$ and is almost orthogonal to that of \mathbf{S}_k , which yields

$$\hat{\mathbf{H}}_{e,k}^H \mathbf{T}_k \mathbf{T}_k^H \hat{\mathbf{H}}_{e,k} \simeq \mathbf{I}_{N_s} \quad \text{and} \quad \mathbf{S}_k^H \mathbf{T}_k \simeq \mathbf{0}. \quad (11)$$

By substituting (5) and (6) and applying (11), the numerator in (10) can be approximated by

$$\begin{aligned} &\rho \text{Tr}(\mathbf{H}_{e,k}^H \mathbf{T}_k \mathbf{T}_k^H \mathbf{H}_{e,k}) \\ &\approx \rho \text{Tr}(\mathbf{A}_{e,k} (\hat{\mathbf{H}}_{e,k} \mathbf{A}_k \mathbf{B}_k)^H \mathbf{T}_k \mathbf{T}_k^H (\hat{\mathbf{H}}_{e,k} \mathbf{A}_k \mathbf{B}_k)) \\ &\approx \rho \text{Tr}(\mathbf{A}_{e,k} \mathbf{B}_k^H \mathbf{A}_k^H \mathbf{A}_k \mathbf{B}_k) \\ &= \rho \text{Tr}(\mathbf{A}_{e,k} (\mathbf{I}_{N_s} - \mathbf{C}_k^H \mathbf{C}_k)) \end{aligned} \quad (12)$$

$$= \rho \text{Tr}(\mathbf{A}_{e,k} \overline{\mathbf{H}}_{e,k}^H \hat{\mathbf{H}}_{e,k} \hat{\mathbf{H}}_{e,k}^H \overline{\mathbf{H}}_{e,k}) \quad (13)$$

where (12) comes from the definitions of \mathbf{A}_k and \mathbf{B}_k and (13) follows from $\mathbf{C}_k^H \mathbf{C}_k = \mathbf{I}_{N_s} - \overline{\mathbf{H}}_{e,k}^H \hat{\mathbf{H}}_{e,k} \hat{\mathbf{H}}_{e,k}^H \overline{\mathbf{H}}_{e,k}$, which is a sufficient condition for \mathbf{C}_k to satisfy its definition $\text{Tr}(\mathbf{C}_k^H \mathbf{C}_k) = d^2(\overline{\mathbf{H}}_{e,k}, \hat{\mathbf{H}}_{e,k})$.

Next, we consider the interference term. By applying (5) and

(6), the j th interference term of (10) is given as

$$\begin{aligned} &\rho \text{Tr}(\mathbb{E}[\mathbf{H}_{e,k}^H \mathbf{T}_j \mathbf{T}_j^H \mathbf{H}_{e,k}]) \\ &= \rho \text{Tr}(\mathbf{A}_{e,k} \mathbb{E}[\overline{\mathbf{H}}_{e,k}^H \mathbf{T}_j \mathbf{T}_j^H \overline{\mathbf{H}}_{e,k}]) \\ &= \rho \text{Tr}(\mathbf{A}_{e,k} \mathbf{C}_k^H \mathbb{E}[\mathbf{S}_k^H \mathbf{T}_j \mathbf{T}_j^H \mathbf{S}_k] \mathbf{C}_k) \end{aligned} \quad (14)$$

$$= \frac{\rho N_r}{N_t - N_r} \text{Tr}(\mathbf{A}_{e,k} \mathbf{C}_k^H \mathbf{C}_k) \quad (15)$$

where we have (14) since the BD makes $\hat{\mathbf{H}}_{e,k}^H \mathbf{T}_j = \mathbf{0}$ for $j \neq k$ and (15) comes from the fact that both \mathbf{S}_k and \mathbf{T}_j are isotropically distributed in the left nullspace of $\hat{\mathbf{H}}_{e,k}$ and independent to each other. Hence, $\mathbf{S}_k^H \mathbf{T}_j \mathbf{T}_j^H \mathbf{S}_k$ is matrix variate beta distributed with parameters N_s and $N_t - 2N_s$, which means $\mathbb{E}[\mathbf{S}_k^H \mathbf{T}_j \mathbf{T}_j^H \mathbf{S}_k] = N_s/(N_t - N_s)$ [13]. Therefore, the total interference term in (10) becomes

$$\begin{aligned} &\sum_{j \neq k} \rho \text{Tr}(\mathbb{E}_{\mathbf{T}_j} [\mathbf{H}_{e,k}^H \mathbf{T}_j \mathbf{T}_j^H \mathbf{H}_{e,k}]) \\ &= \rho \text{Tr}(\mathbf{A}_{e,k} (\mathbf{I}_{N_s} - \overline{\mathbf{H}}_{e,k}^H \hat{\mathbf{H}}_{e,k} \hat{\mathbf{H}}_{e,k}^H \overline{\mathbf{H}}_{e,k})). \end{aligned} \quad (16)$$

Finally, by inserting (13) and (16) into (10), the lower bound of the expected SINR for the k th user can be expressed as

$$\overline{\text{SINR}}_k \gtrsim \frac{\rho \|\mathbf{H}_{e,k}^H \hat{\mathbf{H}}_{e,k}\|_F^2}{\|\mathbf{R}_k\|_F^2 + \rho (\|\mathbf{H}_{e,k}\|_F^2 - \|\mathbf{H}_{e,k}^H \hat{\mathbf{H}}_{e,k}\|_F^2)} \quad (17)$$

$$= \frac{\rho \text{Tr}(\mathbf{A}_{e,k}) - \rho \text{Tr}(\mathbf{A}_{e,k} \mathbf{Z}_k)}{\|\mathbf{R}_k\|_F^2 + \rho \text{Tr}(\mathbf{A}_{e,k} \mathbf{Z}_k)} \triangleq \gamma_k^{\text{SINR}} \quad (18)$$

where \mathbf{Z}_k denotes $\mathbf{Z}_k = \mathbf{C}_k^H \mathbf{C}_k$ and (18) comes from (12) and (15). The outer expectation in (10) vanishes since the signal term does not depend on \mathbf{T}_k any more. It is straightforward to show that (17) or (18) approaches the true SINR in (3) when the CDIs of the selected users are fully orthogonal. This is because in this case, the precoding matrices \mathbf{T}_k simply become the CDIs $\hat{\mathbf{H}}_{e,k}$ fed back by the selected users. More importantly, equation (17) is independent of $\{\mathbf{T}_k\}_{k=1}^{K_s}$ and is only a function of a given CDI $\hat{\mathbf{H}}_{e,k}$ and a receive filter \mathbf{R}_k .

Based on our expected SINR metric (17), we now explain how to obtain the CDI and CQI feedback.

First, we choose the CDI matrix which maximizes (17) according to

$$\hat{\mathbf{H}}_{e,k} = \arg \max_{\mathbf{W}_i \in \mathcal{C}} \frac{\rho \|\mathbf{R}_k^H \mathbf{H}_k^H \mathbf{W}_i\|_F^2}{\|\mathbf{R}_k\|_F^2 + \rho (\|\mathbf{H}_k \mathbf{R}_k\|_F^2 - \|\mathbf{R}_k^H \mathbf{H}_k^H \mathbf{W}_i\|_F^2)}. \quad (19)$$

Here, for computing \mathbf{R}_k , the MMSE receiver (2) is not available since $\{\mathbf{T}_k\}_{k=1}^{K_s}$ is not known yet as discussed before. On the other hand, we know that if K is large, the precoders $\{\mathbf{T}_k\}_{k=1}^{K_s}$ are almost orthogonal to each other, i.e., $\sum_{j=1}^{K_s} \mathbf{T}_j \mathbf{T}_j^H \simeq \mathbf{I}_{N_t}$, and then \mathbf{T}_k can be simply chosen as the CDI. Accordingly, for a given codeword \mathbf{W}_i in (19), we can alternatively compute the MMSE receiver \mathbf{R}_k without the knowledge of $\{\mathbf{T}_k\}_{k=1}^{K_s}$ as

$$\mathbf{R}_k = \left(\mathbf{I}_{N_r} + \rho \mathbf{H}_k^H (\mathbf{I}_{N_t} - \mathbf{W}_i \mathbf{W}_i^H) \mathbf{H}_k \right)^{-1} \mathbf{H}_k^H \mathbf{W}_i. \quad (20)$$

Once the CDI $\hat{\mathbf{H}}_{e,k}$ and the corresponding \mathbf{R}_k are determined by (19) and (20), respectively, the proposed CQI γ_k^{SINR} is directly obtained from (17).

Comparing with the conventional metric γ_k^{nom} in (9), the proposed CQI (17) is expected to closely reflect each user's actual channel quality, since it takes into account the effect of both the BD precoder and the MMSE receiver. Furthermore, it can be seen that the term $\|\mathbf{H}_{e,k}^H \hat{\mathbf{H}}_{e,k}\|_F^2 = \text{Tr}(\mathbf{\Lambda}_{e,k} \bar{\mathbf{H}}_{e,k}^H \hat{\mathbf{H}}_{e,k} \hat{\mathbf{H}}_{e,k}^H \bar{\mathbf{H}}_{e,k})$ in (17) gets larger when $\bar{\mathbf{H}}_{e,k}$ and $\hat{\mathbf{H}}_{e,k}$ are closely aligned. Therefore, γ_k^{SINR} also accounts for the quantization accuracy as well as the channel magnitude. Thus, we expect that the proposed scheme provides good performance also in the interference regime of high P .

Based on the effective channels $\{\gamma_k^{\text{SINR}} \hat{\mathbf{H}}_{e,k}\}_{k=1}^K$ constructed by the CDI and the CQI feedback from users, the BS selects the best K_s users by scheduling and performs the BD precoding as described in Section III. Then, after the transmission, each active user decodes its signal vector \mathbf{u}_k by applying the MMSE receiver of (2) which is now available at the receiver.

V. ASYMPTOTIC ANALYSIS

In this section, we analyze the distribution of the proposed expected SINR-based CQI metric (18). The exact distribution of (18) depends on the Grassmannian packing problem related to \mathbf{Z}_k . However, this analysis is difficult because for finite N_t and N_s , a quantization bound of the subspace packing is not known for $N_s \geq 2$. Alternatively, we seek an asymptotic distribution where both $N_t = \tau N$ and $N_s = N$ simultaneously grow large with a fixed ratio $\tau = N_t/N_s$, which is a useful approach when the exact analysis is mathematically intractable [21], [22]. Later on, it will be shown that our analysis matches well even with the small number of antennas.

In the large antenna regime, γ_k^{SINR} reduces to

$$\lim_{N \rightarrow \infty} \gamma_k^{\text{SINR}} = \frac{\text{Tr}(\mathbf{\Lambda}_{e,k})}{\text{Tr}(\mathbf{\Lambda}_{e,k} \mathbf{Z}_k)} - 1 \quad (21)$$

even if the transmit power level P is finite. We first look at the probability density function (PDF) of (21) and after that the outage probability will be evaluated. The central limit theorem is useful to sketch the context of the work here.

A. Approximate Density Function

Denote the two terms $\text{Tr}(\mathbf{\Lambda}_{e,k})$ and $\text{Tr}(\mathbf{\Lambda}_{e,k} \mathbf{Z}_k)$ in (21) by X and Y , respectively. Then, we present the following two lemmas.

Lemma 1: As N goes to infinity, X follows

$$X \sim \mathcal{N}(\mu_X, \sigma_X^2) \quad (22)$$

where $\mu_X = \sigma_X^2 = \tau N^2$.

Proof: Since $\text{Tr}(\mathbf{\Lambda}_{e,k}) = \sum_{i=1}^{N_t} \sum_{j=1}^{N_s} |h_{ij}|^2$ is a sum of independent and identically distributed random variables, the central limit theorem says that X is asymptotically normal [23]. The mean and the variance of $\text{Tr}(\mathbf{\Lambda}_{e,k})$, a sum of unordered eigenvalues of the complex Wishart matrix $\mathbf{H}_{e,k} \mathbf{H}_{e,k}^H$, are commonly known, for example, in [21]. \square

Lemma 2: When the random codeword selection is assumed for the decision of $\hat{\mathbf{H}}_{e,k}$, Y is given approximately with large N by

$$Y \sim \mathcal{N}(\mu_Y, \sigma_Y^2) \quad (23)$$

where we have $\mu_Y = (\tau - 1)N^2$ and $\sigma_Y^2 \approx \xi N^2$, and ξ is defined as $\xi \triangleq (\tau^2 + 1)(\tau - 1)/\tau^2$.

Proof: See Appendix. \square

In deriving Lemma 2, we have assumed that an arbitrary codeword is selected in the codebook \mathcal{C} for the ease of analysis, which corresponds to the worst case of channel quantization. This provides a lower bound on the actual system performance. If N_t is sufficiently large compared to the number of bits B , our results hold with practical codebook selection methods such as (7). Under the same assumption, the cross-correlation of X and Y can be computed as $\mathbb{E}[XY] = (\tau - 1)(\tau N^2 + 1)N^2$ by adopting the same approach used in the Appendix. Then, from the above two lemmas, the correlation coefficient ρ_{XY} between X and Y is obtained as

$$\rho_{XY} = \frac{\mathbb{E}[XY] - \mu_X \mu_Y}{\sigma_X \sigma_Y} \approx \frac{\tau - 1}{\sqrt{\tau \xi}}. \quad (24)$$

Now, we have two Gaussian random variables X and Y with the correlation coefficient ρ_{XY} . In this case, the distribution of $V = X/Y$, called as the Gaussian ratio distribution, is known as a closed-form in [24]. We use this result to get the approximate PDF of (21) in the limit of large N , which yields

$$\begin{aligned} f_\gamma(x) &\approx \frac{\sqrt{\omega}}{\pi g(x+1)} e^{-\frac{\tau N^2}{2}} \\ &- \frac{\omega N(x+1)}{\pi g(x+1)^{1.5}} e^{-\frac{N^2(1-(\tau-1)x)^2}{2g(x+1)}} \Theta\left(-\frac{\sqrt{\omega}N(x+1)}{g(x+1)^{0.5}}\right) \end{aligned} \quad (25)$$

where we have

$$\begin{aligned} g(x) &= \xi x^2 - 2(\tau - 1)x + \tau, \quad \omega = \tau - \tau^{-1}, \\ \Theta(y) &= \int_0^y e^{-u^2/2} du. \end{aligned}$$

In Fig. 2, we compare the asymptotic approximation for $f_\gamma(x)$ with the simulated results where 100,000 Monte Carlo runs were carried out. From this figure, it can be seen that the analytical and empirical results match closely even for the small number of antennas $N_t = 8$ and $N_s = 4$. Thus, the validity of the asymptotic analysis can be confirmed.

B. Outage Probability

From (25), the CDF of γ_k^{SINR} is found by direct calculation to be [25]

$$\begin{aligned} F_\gamma(x) &\approx L \left\{ \frac{N - (\tau - 1)Nx}{g(x+1)^{0.5}}, -\frac{(\tau - 1)N}{\sqrt{\omega}}; \frac{\xi x + \xi - \tau + 1}{\sqrt{\omega}g(x+1)^{0.5}} \right\} \\ &+ L \left\{ \frac{(\tau - 1)Nx - N}{g(x+1)^{0.5}}, \frac{(\tau - 1)N}{\sqrt{\omega}}; \frac{\xi x + \xi - \tau + 1}{\sqrt{\omega}g(x+1)^{0.5}} \right\} \end{aligned} \quad (26)$$

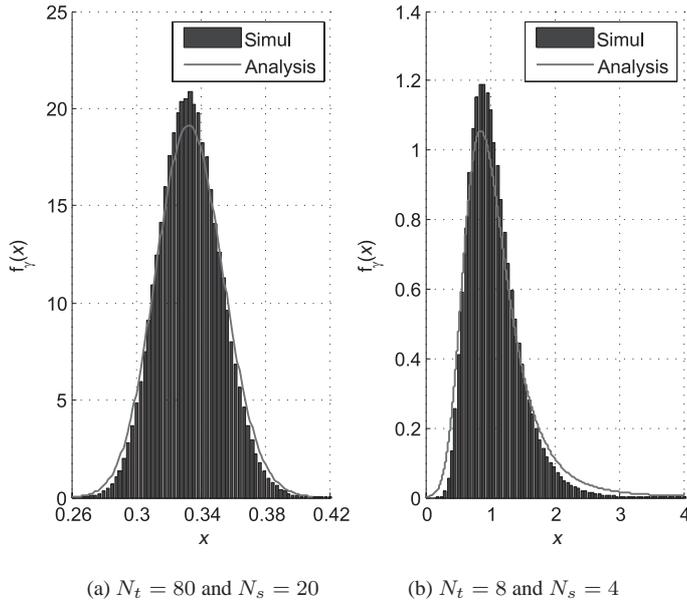


Fig. 2. Comparison of the simulated and asymptotic theoretical PDF of γ_k^{SINR} .

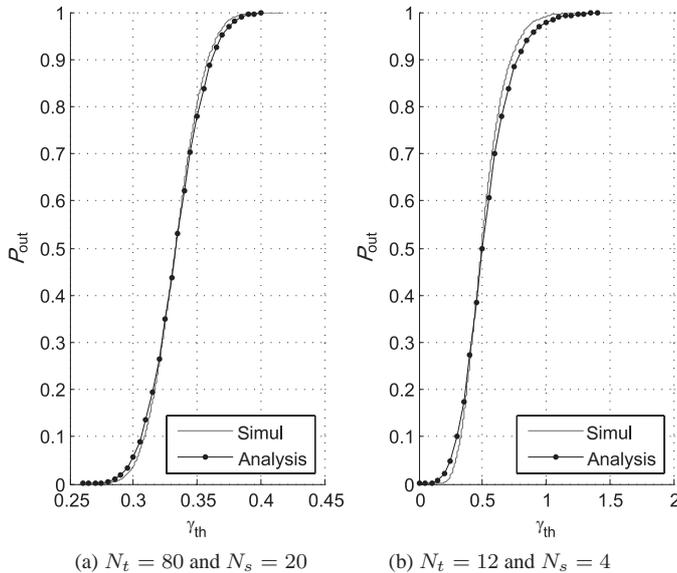


Fig. 3. Outage probability of γ_k^{SINR} .

where $L\{m, n; r\}$ is the standard bivariate normal integral given by [26]

$$L\{m, n; r\} = \frac{1}{2\pi\sqrt{1-r^2}} \int_m^\infty \int_n^\infty e^{-\frac{x^2+y^2-2rxy}{2(1-r^2)}} dx dy.$$

The expression (26) is quite complicated. However, in the asymptotic regime of $N \rightarrow \infty$, (26) is simplified as [25]

$$F_\gamma(x) \xrightarrow{\text{a.s.}} 1 - Q\left(\frac{(\tau-1)Nx - N}{g(x+1)^{0.5}}\right)$$

where $\xrightarrow{\text{a.s.}}$ denotes the asymptotic convergence and $Q(\cdot)$ is the Gaussian Q-function.

Therefore, the outage probability that γ_k^{SINR} is below a certain

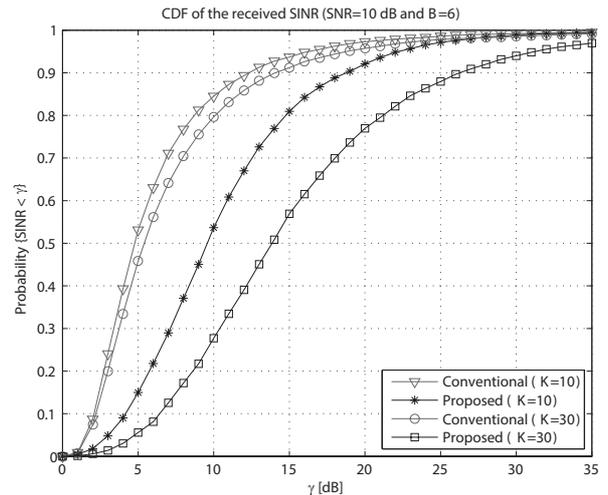


Fig. 4. CDF of the received SINR for $N_t = 4$ and $N_r = 2$ with $K = 10$ and 30 users.

SINR threshold γ_{th} , $P_{\text{out}} \triangleq P\{\gamma_k^{\text{SINR}} \leq \gamma_{\text{th}}\}$ can be evaluated as

$$P_{\text{out}} \approx 1 - Q\left(\frac{(\tau-1)N\gamma_{\text{th}} - N}{g(\gamma_{\text{th}}+1)^{0.5}}\right). \quad (27)$$

For a given desired outage probability P_{out} , γ_{th} can be obtained by solving equation (27). Fig. 3 plots the outage probability (27) for different numbers of antennas. Also the simulated cumulative distributions are displayed for comparison. By comparing the results, we note that our asymptotic approximation is accurate even for the moderate number of N_t and N_s as well as the large system case.

VI. SIMULATION RESULTS

In this section, we investigate the sum rate performance of multiuser MIMO downlink systems employing the BD precoding and the proposed limited feedback scheme. For all simulations, we use spatially uncorrelated MIMO Rayleigh fading channels which are independently generated for each transmission. We assume that each user adopts different codebooks to prevent a case where more than two users choose the same codebook. For user scheduling, we apply the SUS algorithm proposed in [4] by slightly modifying the operations so as to be applicable to the multi-stream case of $N_s > 1$ with the threshold parameter $\alpha = 0.5$ and 0.4 for $N_t = 4$ and 6, respectively.

In Fig. 4, we plot the cumulative distribution function (CDF) of the average received SINR for the scheduled users under two different feedback schemes for $(N_t, N_r) = (4, 2)$ and $N_s = 2$ at the SNR of 10 dB. The average SINR is defined as $1/K_s \sum_{k=1}^{K_s} \text{SINR}_k$ from (3). In this plot, we observe that the proposed SINR feedback outperforms the magnitude feedback in (9) for both $K = 10$ and 30 users. We emphasize that when the magnitude feedback scheme is applied, a multiuser diversity gain is marginal even with a large number of users, as it fails to exploit multiuser diversity. In contrast, our feedback scheme significantly improves the SINR with increasing users,

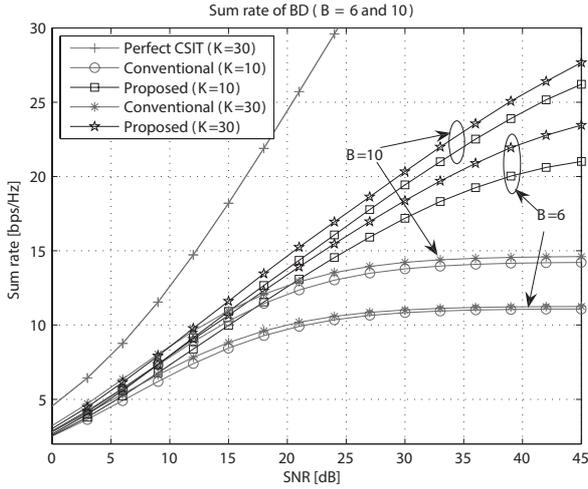


Fig. 5. Sum rates for $(N_t, N_r) = (4, 2)$ and $N_s = 2$ with $K = 10$ and 30 users.

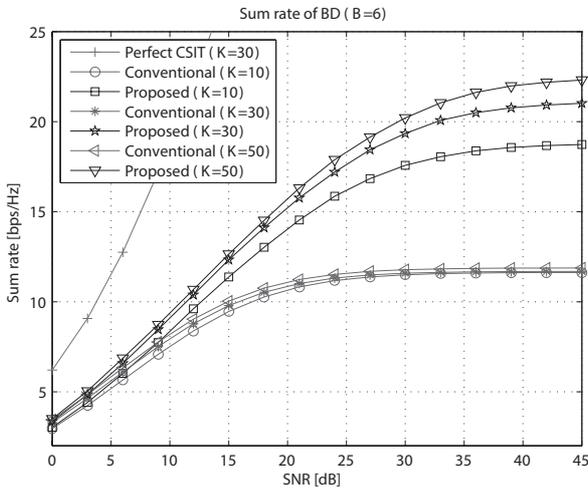


Fig. 6. Sum rates for $(N_t, N_r) = (6, 3)$ and $N_s = 2$ with $K = 10, 30$ and 50 users.

which implies that the proposed expected SINR metric (17) is effective in utilizing the multiuser diversity gain.

Figs. 5 and 6 show the sum rate comparison between the conventional and the proposed channel quantization method for $(N_t, N_r) = (4, 2)$ and $(N_t, N_r) = (6, 3)$, respectively, with $N_s = 2$. Different from the perfect CSI case², the sum rates with limited feedback are saturated as $P \rightarrow \infty$ due to unavoidable residual interference which comes from the CDI quantization error. We confirm that as expected from Fig. 4, our SINR-based feedback strategy outperforms the conventional scheme with the practical codebook size $B = 6$ and 10, especially at high SNR. The sum rate gains of the proposed SINR feedback scheme are roughly 100% over the magnitude feedback method at the high SNR region for $K = 10, 30$, and 50 users. This is

²For the antenna setting of Fig. 6, the best known technique with full CSI is the so-called coordinated beamforming [15]. However, in this simulation, we have simply performed the BD at the transmitter with the feedback of dominant channel eigenmodes.

because the magnitude feedback does not reflect the amount of the quantization error which dominates the performance of multiuser systems for large P . Note that a scheduling gain of the proposed scheme becomes larger as K increases.

VII. CONCLUSIONS

In this paper, we have investigated the issue of limited feedback for BD precoded MIMO BCs along with the user selection process. In order to appreciate a multiuser diversity gain, we have proposed an efficient CDI and CQI quantization technique based on a derivation of the received SINR for each user by evaluating the average received SINR for each user. Also, we have performed an asymptotic analysis on the distribution of the proposed CQI metric. From simulations, we have verified that by reflecting both the channel gain and the quantization error, the proposed SINR-based channel quantization outperforms the conventional feedback in practical BD system environments.

APPENDIX

A. Proof of Lemma 2

First, we examine the asymptotic behavior of the distribution of Y under the assumption of the random codeword selection. In that case, \mathbf{Z}_k follows the matrix variate beta distribution $\beta(N_t - N_r, N_r)$ [13]. Then, each diagonal entry of \mathbf{Z}_k , $z_{k,i}$ ($i = 1, \dots, N_r$) is also beta distributed with parameters $N_t - N_r$ and N_r [27]. Considering that the unordered eigenvalues $\lambda_{k,1}, \dots, \lambda_{k,N_r}$ are also homogeneous in distribution, we confirm that $\{\lambda_{k,i} z_{k,i}\}_{i=1}^{N_r}$ are identically distributed.

The correlation coefficient ρ_{ij} between $\lambda_{k,i} z_{k,i}$ and $\lambda_{k,j} z_{k,j}$ for $i \neq j$ can be shown to be approximated by

$$\rho_{ij} \approx -\frac{(\tau - 1)(\tau N + 1)}{\tau((\tau - 1)N + 2)N^2}. \quad (28)$$

For brevity, the derivations are omitted here. We can easily see that (28) asymptotically converges to zero with $N \rightarrow \infty$, which means that $\lambda_{k,1} z_{k,1}, \dots, \lambda_{k,N_r} z_{k,N_r}$ are uncorrelated. Therefore, the central limit theorem proves that $Y = \sum_{i=1}^{N_r} \lambda_{k,i} z_{k,i}$ follows an asymptotically normal distribution.

In the following, we evaluate the mean and the variance of Y , by using the fact that the first and the second moment of the beta random variable $z_{k,i}$ are given by $\mathbb{E}[z_{k,i}] = (N_t - N_r)/N_t$ and $\mathbb{E}[z_{k,i}^2] = (N_t - N_r)(N_t - N_r + 1)/\{N_t(N_t + 1)\}$, respectively. At first, we obtain μ_Y as

$$\begin{aligned} \mu_Y &= \mathbb{E} \left[\sum_{i=1}^{N_r} \lambda_{k,i} z_{k,i} \right] \\ &= N_t \sum_{i=1}^{N_r} \mathbb{E}[z_{k,i}] = N_r(N_t - N_r) = (\tau - 1)N^2 \end{aligned} \quad (29)$$

where the second equality holds since $\lambda_{k,i}$ and $z_{k,i}$ are independent.

Next, the second moment of Y can be expressed as

$$\begin{aligned}\mathbb{E}[Y^2] &= \mathbb{E}\left[\sum_{i=1}^{N_r} \lambda_{k,i} z_{k,i} \sum_{j=1}^{N_r} \lambda_{k,j} z_{k,j}\right] \\ &= \sum_{i=1}^{N_r} \mathbb{E}[\lambda_{k,i}^2] \mathbb{E}[z_{k,i}^2] \\ &\quad + \sum_{i=1}^{N_r} \sum_{j=1, j \neq i}^{N_r} \mathbb{E}[\lambda_{k,i} \lambda_{k,j}] \mathbb{E}[z_{k,i} z_{k,j}].\end{aligned}\quad (30)$$

Here, $\mathbb{E}[\lambda_{k,i}^2]$, $\mathbb{E}[z_{k,i}^2]$, and $\mathbb{E}[\lambda_{k,i} \lambda_{k,j}]$ in (30) are well known. Also, noting that

$$\begin{aligned}\text{cov}(z_{k,i}, z_{k,j}) &= \mathbb{E}[z_{k,i} z_{k,j}] - \mathbb{E}[z_{k,i}] \mathbb{E}[z_{k,j}] \\ &= \frac{N_r(N_t - N_r)}{N_t^2(N_t + 1)} \xrightarrow{\text{a.s.}} 0\end{aligned}$$

we can replace the last term $\mathbb{E}[z_{k,i} z_{k,j}]$ by $\mathbb{E}[z_{k,i}] \mathbb{E}[z_{k,j}]$. Then, after some calculations, (30) reduces to a function of N and τ as

$$\begin{aligned}\mathbb{E}[Y^2] &= \frac{(\tau^2 - 1)((\tau - 1)N + 1)N^3}{\tau N + 1} \\ &\quad + \frac{(\tau - 1)^2(\tau N - 1)(N - 1)N^2}{\tau}.\end{aligned}\quad (31)$$

Now, from (29) and (31), the variance σ_Y^2 is given as

$$\begin{aligned}\sigma_Y^2 &= \mathbb{E}[Y^2] - \mu_Y^2 \\ &= N^2 \left(\frac{(\tau^2 + 1)(\tau - 1)}{\tau^2} - \frac{\tau^2 - 1}{\tau^2(\tau N + 1)} \right) \\ &\approx \frac{(\tau^2 + 1)(\tau - 1)}{\tau^2} N^2.\end{aligned}\quad (32)$$

Here, the second term of (32) is neglected for large N .

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